

Original declaration of
incorporation with manual for

ARIS Valve Actuator Ventaris N⁺

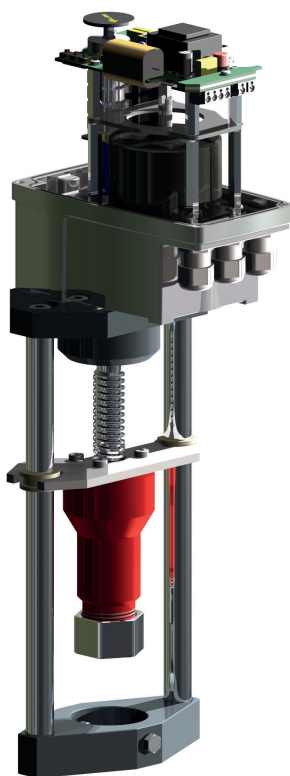


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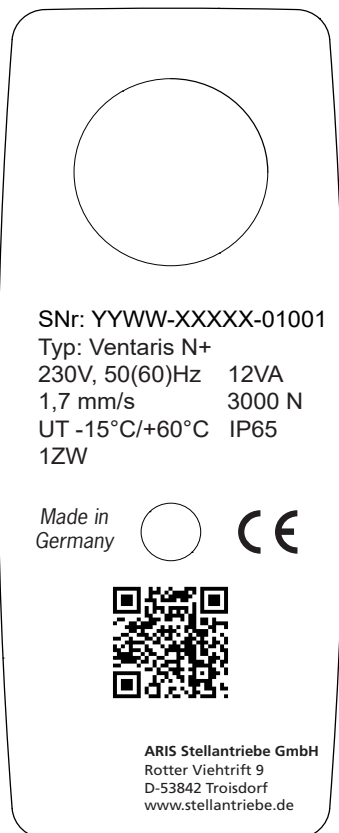
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1. Identification

This manual is valid for:

Description: Electric actuator
Type: Ventaris N+
Serial no.: YYWW-xxxx-01001 ff.

1.1 Nameplate



- ← Serial number (YYWW = Baujahr+Woche)
- ← Actuator type
- ← Voltage/Frequency/Power consumption
- ← Actuating time/Force
- ← Ambient temperature/Protection class
- ← Additional built-in parts

1.2 Guidelines and standards

ARIS actuators are partly completed machinery according to directive 2006/42/EC. This is certified by a declaration of incorporation (see page 33).

Further applicable EC directives:	EMC Directive 2014/30/EU	
Applied harmonized standards:	LVD 2006/95/EG	DIN EN 61010-1:2011-07
	MachDir 2006/42/EG	DIN EN 12100:2011-03
	EMC Directive 2004/108/EG	DIN EN 61000-3-2
		DIN EN 61000-3-3
		DIN EN 61000-6-2
		DIN EN 61000-6-3
		DIN EN 55011:2001-04
		DIN EN 61000-6-4:2011-09
Protection classes by housing (IP-Codes):	Protection class test	DIN EN 60529:1991



ADVICE

EMC consideration of the complete plant and system perturbations and their combating have to be carried out by the plant builder or operator. The wiring of the actuator should comply with DIN EN 60204-1.

2. Safety information

2.1 Warnings

Installation and initial operation only by certified experts according to the manual.

Observe the significance of the following symbol and note explanations. They are subdivided in security levels and classified according to ISO 3864-2.

	DANGER indicates a hazard with a high risk degree, which, if not avoided, causes death or heavy injuries.
	WARNING indicates a hazard with a medium risk degree, which, if not avoided, can cause death or heavy injuries.
	CAUTION indicates a hazard with a low risk degree, which, if not avoided, can cause slight or moderate injuries.
	Indicates general advices, useful hints and work recommendations, which don't have influence on the safety and health of the staff.

2.2 General safety advices

The actuator components are conform to the state of the art and apply as generally safe at the time they are shipped.

This manual serves as basis to install and operate ARIS actuators safety conform. All persons working with or on ARIS actuators must observe this manual and especially its safety advices.

	• This manual has to be kept at the operating place at any time. • Read the manual carefully prior to installation and initial operation.
	Certain parts of active electric appliances are obligatory under voltage.

- Working on electric appliances or equipment is only allowed for electrically qualified persons or other instructed persons under guidance and custody of an electrically qualified person according to the electro-technical regulations.
- Observe all safety and accident prevention regulations while installing, operating and testing any electrical appliances or machinery.
- Prior to all installation or regular work on the actuator make sure to switch off all connected machinery/appliances.

3. Technical specification

3.1 Function and application areas (Intended use)

ARIS actuators are exclusively designed for industrial use. ARIS actuators of type VENTARIS are utilized for operating regulating and shut-off appliances (valves, slide valves, etc.).

ARIS actuators may not be used

- at temperatures above or below the specified technical data,
- within underground environments,
- near open fire,
- under water.

3.2 Safe and accurate use

ARIS actuators are factory checked prior to delivery. The final functional testing must be performed within the total system by qualified technical personnel.

The ARIS company assumes no liability for possible manufacturing errors and resulting damages or subsequent damages when

- the actuator was not sufficiently tested within the complete system,
- the actuator was used inappropriately,
- the actuator has not been put out of operation after a failure has been determined.

Conduct frequent checks during operation. Pay special attention to:

- Intended usage of the actuator (chapter 3.1);
- abnormal noise, strong vibrations or raised temperatures;
- fastening screws, cable inputs, cable glands and plugs with proper tightening torque and leakage;
- condition of electrical wires.

In case of failures, set the actuator out of operation and fix the malfunction.

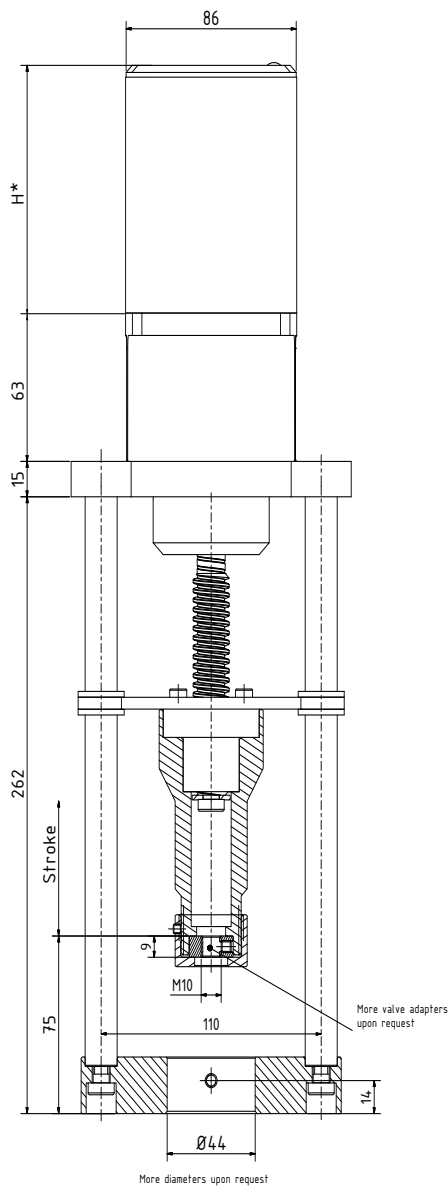
All persons dealing with installation, setup and initial operation must

- be specially trained and qualified;
 - mentally and physically capable;
 - observe the manual.
-
- Valves, levers and connecting rods are moving during actuator operation;
 - Check for proper function of all emergency equipment on your machinery;
 - Check for proper function of the actuator and operated valves after completion of all installation work;
 - Never work with or operate a faulty actuator.

3.3 Dimensions

Ventaris N+

*H = max. 145 mm



Force (N)	1000	1000	1000	1000	1000	2000	2000	2000	2000	2000	3000	3000
Time (mm/s)	0.1	0.3	0.5	0.8	1.3	0.1	0.3	0.5	0.8	1.3	0.1	0.3

Force (N)	3000	3000	3000	4000	4000	4000	4000	4000	5000	5000	5000	6000
Time (mm/s)	0.5	0.8	1.3	0.1	0.3	0.5	0.8	1.3	0.1	0.3	0.5	0.7

3.4 Performance data

- **Protection class: IP65**
- **Motor: 230 V $\pm 10\%$, 50/60Hz $\pm 5\%$, 100% ED (Standard)**
 - » Special voltage/-frequency see nameplate (Option)
 - » Insulation class E acc. DIN EN 60034-1
- **Motor: 24 V DC (Option) $\pm 20\%$, ED S3 50%**
 - » Insulation class B acc. DIN EN 60034-1
- **Connection: 3 cable glands M16x1.5 (Customer provided)**
- **Path cut-off: Aluminum cams, micro switches**
 - » Switching capacity max. 10(3) A, 250V AC
- **Ambient temperature**
 - » -15 °C bis +60 °C (optional -40 °C...+80 °C)
- **Installation position: Arbitrary**
- **Potentiometer (Option)**
 - » Recommended wiper current: 0,2 μ A
 - » Capacity at +70 °C: 0,5 W
- **Travel: 50 mm**
- **Force: max. 6000N**

3.5 Expected lifespan and intended disposal

ARIS actuators have an expected lifespan of several years, depending on their utilization and application. No longer usable actuators must not be dismantled as a whole, but separately recycled in parts divided by their materials. Non-recyclable components must be disposed according to national disposal regulations.

4. Actuator setup for operation

4.1 Transport, (temporary) storage and downtimes

Use the factory packaging for transport to the installation point. Replace a damaged original packaging by a new solid packaging.

- Stellantriebe mit angebauter Armatur: Hebezeug nur an der Armatur befestigen und NICHT am Stellantrieb;
- ARIS Antriebe dürfen nicht als Steig- oder Abstützhilfe benutzt werden;
- ARIS Antriebe dürfen ohne weitere Applikationen nicht im ungesicherten Hebebetrieb betrieben werden



ADVICE

Damage by wrong storage

- Store in well-ventilated rooms;
- Protection against possible ground humidity (shelf storage).
- On long storage times place humidity absorbing agents inside the actuator.
- Protect the actuators against dust and dirt.
- Avoid condensation (e.g. by temperature variation).

4.2 Packaging

ARIS actuators are protected by special cardboard packaging at delivery.

4.3 Safe disposal of packaging

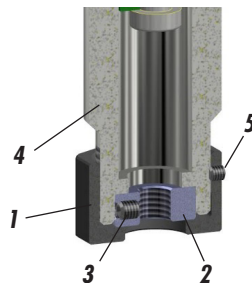
Additionally necessary packaging is made by easily separable packaging materials and can be recycled individually: Wood, cardboard, paper, plastics

4.4 Installation and mounting

- Inspect the actuator for damages prior to installation;
- check leak tightness of cable glands and blank plugs prior to initial operation;
- tighten the cover screws evenly;
- do not operate before limit switches have been adjusted;
- protect the actuator against climatic influences (e.g. by a protective cover);
- do not expose the actuator to hard shocks (e.g. by dropping);
- do not attach ropes, hooks or the like to the actuator;
- permanent overload and blocking leads to actuator damages;
- spark suppressor capacitor can effect the rotation stability of the actuators and may cause damages;
- use only ARIS original spare parts.

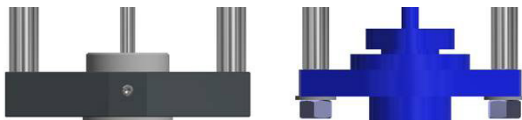
Connecting to the valve spindle:

- Place union nut (1) over the valve spindle
- Screw (or set, depending on type) the driver (2) onto the valve spindle
- Tighten the safety screw (3) (depending on type)
- Insert the driver in to the spindle nut carrier (4)
- Screw the union nut on and fix it with the safety screw (5)



Consider prior to attachment of couplings:

- Do not turn the thread spindle by force



Installation position: The actuators can be installed position independently.

ADVICE

Protection class IP65 (Option IP 66)

For all actuators observe the following advices:

The initial operation of the actuator is only permitted with orderly closed cover and closed cable entries. Use only cable glands which are appropriate for the respective protection class.

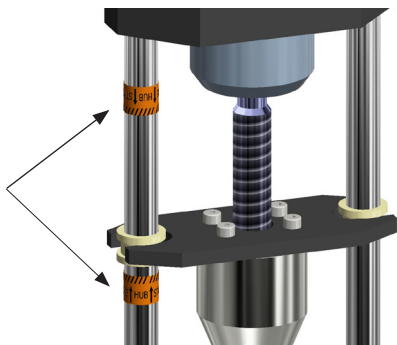
- Cable entries
Ensure that all cable entries are closed properly during storage, installation and initial operation.
Use only cables which are suitable for the diameter of the cable entries.
- Cover assembly
During the cover assembly make sure that the cover fits correctly.
The cover must not show any damages on the joint surface.
Tighten cover screws evenly (max. 1.2 Nm).

ATTENTION

No additional bores are allowed in the housing and the cover.

Stroke range

The usable stroke range of 50 mm is marked by decals on the anti-twist protections and may not be overrun. This may lead to damages to the stroke unit.



4.5 Initial operation

4.5.1 Electrical connection



Hazardous voltage: Possible stroke!

- The initial operation must be carried out only by experts!
- De-energize the actuator before opening.
- Observe the appropriate regulations during electrical installation and initial operation.

Connect the actuator as follows (refer to the wiring diagram at 4.5.2):

- Connect the ground wire of the electric supply to the appropriate protective earth terminal.
- Connect the neutral N to terminal 1.
- Follow the steps under „Set up rotation direction“ (S. 13) during connection of the actuator.
- Always refer to the wiring diagram located inside the actuator.

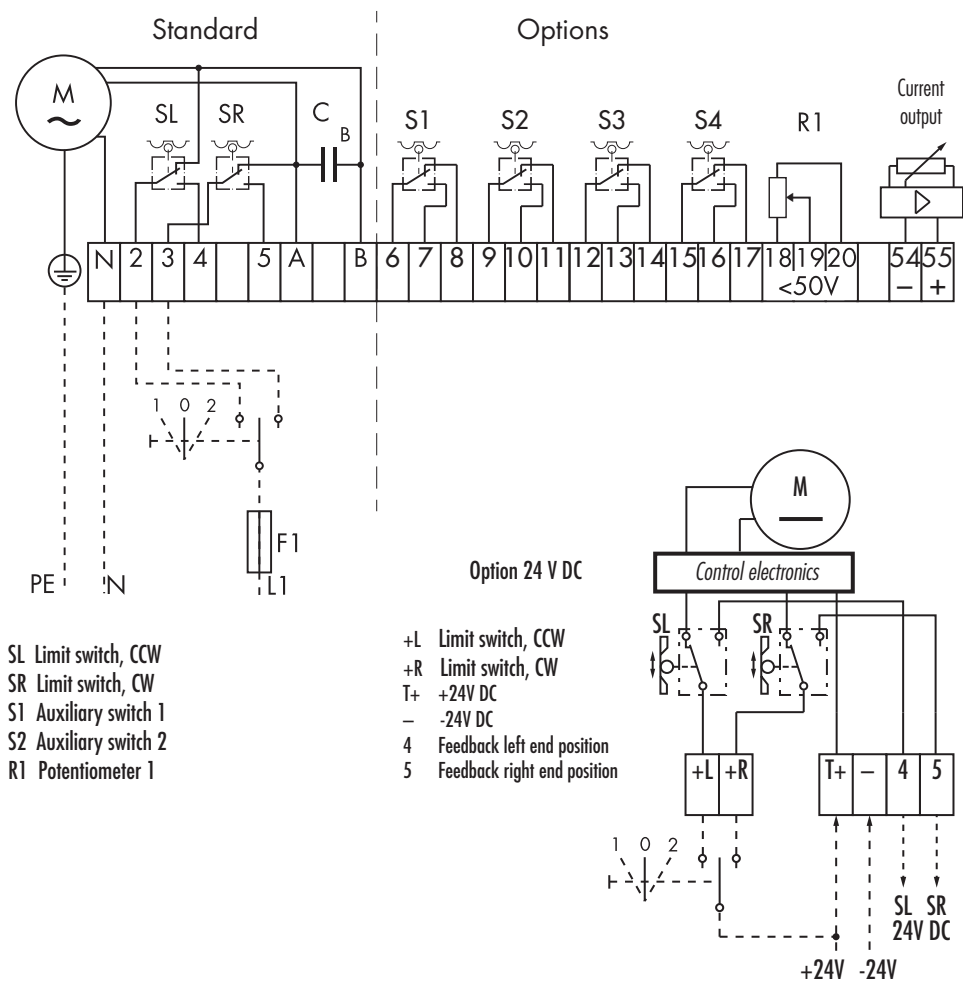
Check before you close the circuit for the first time:

- Is the actuator undamaged on the outside?
- Is the mechanical connection correct?
- Has the electrical connection been made regularly?
- Check if current type, voltage and frequency match with the motor data (see nameplate on cover and inside the actuator).
- Insert suitable cable glands for the connection line.
- Observe the wiring diagram inside the cover.
- Use separate (shielded) wires for low voltages (e.g. potentiometer).
- Set up limit switches prior to initial operation (see page 12).



All elements, such as switches, potentiometer etc., are factory-wired. Never change the internal wiring.

4.5.2 Wiring diagram



! ADVICE

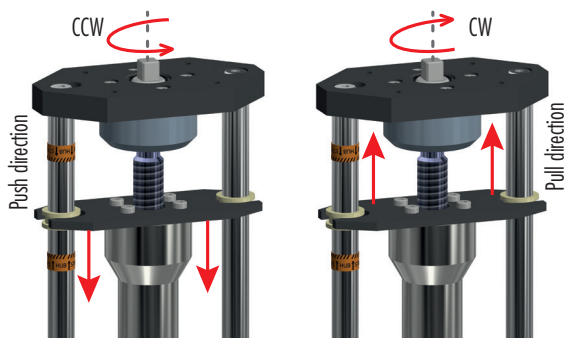
All auxiliary switches must be operated within the same voltage range. Do not mix line voltage with low voltage.

5. Operation of the actuators

5.1 Set up rotation and stroke direction

Due to the internal wiring, the rotation direction (viewing direction is through the actuator towards the shaft) and the limit switches assign as follows:

1. With line voltage on terminal 1 and 2, the actuator shaft rotates **counter-clockwise**. Limitation of this rotation direction with upper switch SL. When the switch is activated, line voltage is on terminal 4.
2. With line voltage on terminal 1 and 3, the actuator shaft rotates **clockwise**. Limitation of this rotation direction with lower switch SR. When the switch is activated, line voltage is on terminal 5.
3. If the actuator runs counterrotating to the commands, change the external connection of terminal 2 and 3.



! ADVICE

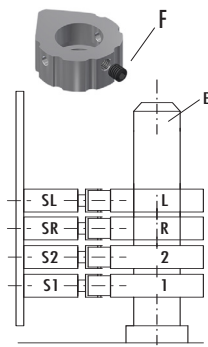
Depending on the model, limit switches may be arranged different than drawn in the wiring diagram (see wiring diagram inside the actuator).

5.2 Set up limit switches (Self-adjusting switch cam)

! ADVICE

The switch cams are turnable by hand and can be fastened by a thread pin, e.g. if strong vibrations apply.

1. Apply voltage (see page 11): Actuator rotates in given direction.
2. Switch off voltage when the desired end position has reached (no blocking of gear).
3. Turn switch cam L in rotating direction of the cam shaft E until limit path switch SL clicks. Now the thread pin F can be fixed with a hex wrench (enclosed).
4. Set up switch cam R for contrary rotating direction as described under step 1–3.
5. Check setup by moving the actuator again electrically and adjust if necessary.

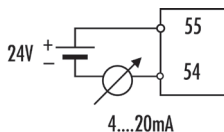


5.3 Optional modules and extra features

5.3.1 Potentiometer

Electrical connection

Connect terminals 18, 19 and 20 according to the desired requirements (voltage $\leq 50V$); (see page 11). Use only separate (shielded) wires.



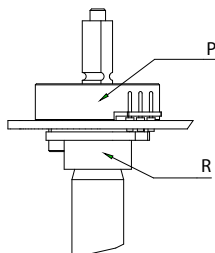
Adjustment

Set up limit switch before adjusting the potentiometer P. Approach both end positions electrically (see chapter 5.2).

Observe travel and potentiometer solution.

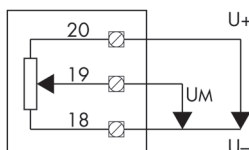
Do not overrun the ordered travel to avoid damage to the friction clutch R by permanent override. Potentiometer P adjusts roughly automatically.

The travel of the valve is transferred to the rotating angle of the potentiometer by the friction clutch R. Approach both end positions again electrically and adjust potentiometer P with the friction clutch R.



! ADVICE

All pots must generally run under a potential divider circuit.

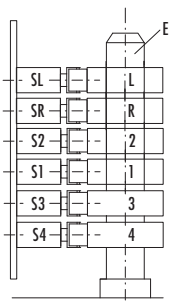


5.3.2 Two of four additional limit switches (Self-adjusting switch cam)

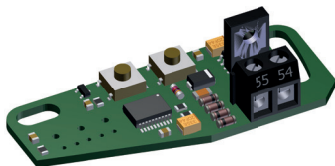
! ADVICE

The switch cams can be rotated by hand and can additionally be fixed with a thread pin, e.g. at strong vibrations.

1. Approach desired position. Switching position must be approached from the desired rotating direction.
2. Turn switch cams „1“ to „4“ in rotating direction of the cam shaft E until limit switch „S1“ to „S4“ clicks. Now the thread pin F can be fixed with a hex wrench (enclosed).
3. Check setup by moving the actuator again electrically and adjust if necessary.



5.3.3 2-wire-current output 4-20 mA (AC only)



Electrical connection

Connect terminal 54 and 55 according to the wiring diagram (see page 12). Use separate (shielded) wire with minimum diameter of 0.5 mm² and a max. length of 1000 m.

Setup

Operate the current output via buttons „4“ and „20“. Assigning arbitrary positions for 4 mA and 20 mA is possible at any time. The lower and upper current limit (4/20 mA) is programmed steady.

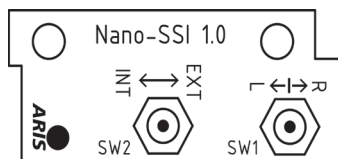
a) Assignment of end position 4 mA:

- Approach end position;
- press button „4“ more than 2 sec.;
- release button „4“;
- the end position is programmed and active at once.

b) Assignment of end position 20 mA:

- Approach end position;
- press button „20“ more than 2 sec.;
- release button „20“;
- the end position is programmed and active at once.

5.3.4 Service switch (AC only)



Adjusting and service work can be done by using the service switch.

Operation:

Set the switch „SW2“ to „INT“ „Manual operation“. The actuator can now be moved via the switch „SW1“ left (position „L“) or right (position „R“).

For operation by an external controller, set the switch „SW2“ to „EXT“. Switch „SW1“ is without function now.

5.3.5 Heating resistant (AC only)



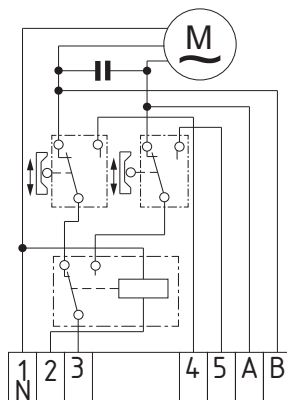
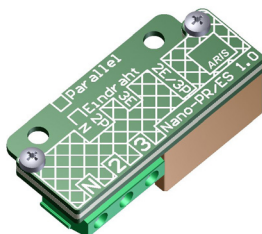
Heating element for use of actuators in cold-humid environments. To avoid condensation water inside the actuator at fluctuating temperatures.

! ADVICE

The heater resistant is wired at factory. Never change the internal wiring. Observe the wiring diagram inside the actuator cover.

5.3.6 Single wire control (AC only)

For use as open/close regulation by external controller or switching appliances with normally open or break contact. The rotation direction reverse is made by a built-in switching relay.

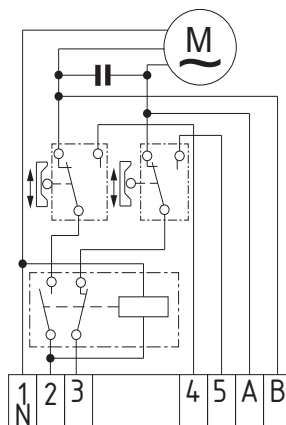
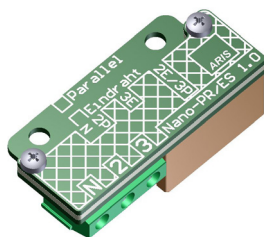


! ADVICE

The add-on board with the single wire control is wired at factory. Never change the internal wiring. Observe the wiring diagram inside the actuator cover.

5.3.7 Parallel relays (AC only)

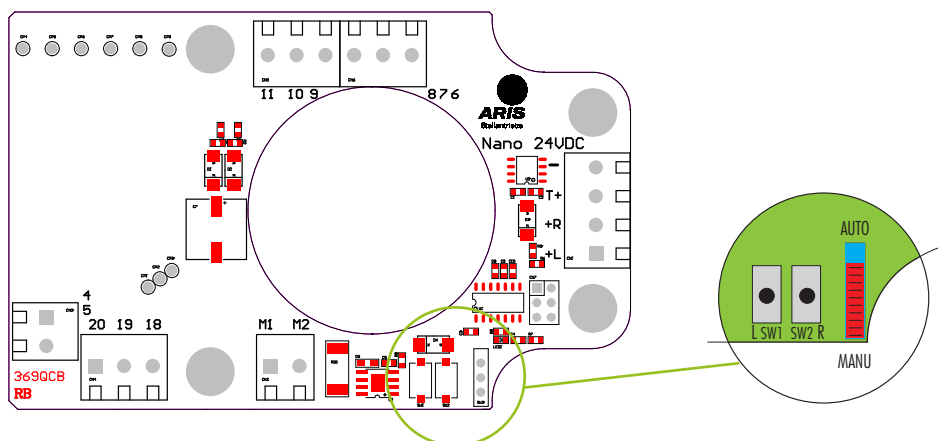
The integrated relay makes it possible to run several actuators in parallel mode over one switching contact.



! ADVICE

The add-on board with the parallel relay is wired at factory. Never change the internal wiring. Observe the wiring diagram inside the actuator cover.

Power supply 24 V DC (Special edition)



5.3.7.1 Service switch (DC only)

Use the service switch to perform adjustment and service works on the actuator. For this, terminal T+ must hold a direct current of 24 V DC.

Operation:

Set the sliding switch to „MANU“ (manual operation). The actuator can now be moved left with the button „L SW1“ (position „L“) or right with the button „R SW2“ (position „R“). For operation via an external controller set the sliding switch to „AUTO“. The buttons „L SW1“ and „R SW2“ are without function now.



The actuating time of an actuator with direct current motor changes load dependant. The indicated actuating time refers to an actuator load with the indicated torque (see name plate).

6. Required customer information

6.1 Extraordinary situations

If failure appear, set the actuator out of order and fix the malfunction.

 ADVICE	If you can not correct the error, contact an ARIS service person. More information under: www.stellantriebe.de
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6.2 Troubleshooting and repair

 WARNING	Hazardous voltage: Possible stroke! • Troubleshooting and repair only by experts! • Cut off voltage before opening the actuator.
 ATTENTION	Moving parts at built-on valves: Possible bruise! • Troubleshooting and repair only by experts!
 ADVICE	We recommend a repair at the ARIS factory. More information under: www.stellantriebe.de

7. Maintenance

7.1 Service

ARIS actuators of type Ventaris have a lifetime lubrication and are generally maintenance-free.
The drive head is changeable separately.



Dismount all additional parts (valve or rods) before exchanging the drive head! Dismount the drive head only under a load-free condition.

Linear unit



We recommend a visible and functional actuator check during plant service work, but at least once a year.

7.2 Accessories

No special tools are required for installation. The required hex wrench is enclosed with the delivery.

7.3 Spare parts



Order spare parts at aris@stellantriebe.de any time.
Please always give the serial number of the actuator.

Technische Änderungen vorbehalten.

ARIS Stellantriebe GmbH
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Fax: +49 2241 25186-99
aris@stellantriebe.de



Manual for

ARIS Microprocessor- Controller PMR-Nano

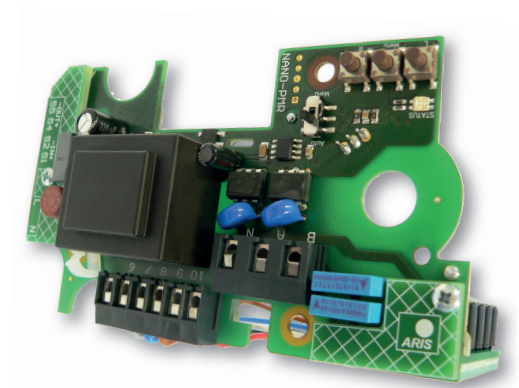


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Intended use

ARIS microprocessor controllers, series PMR-Nano, are used for activating ARIS actuators. They are integrated in the actuator housing. PMR-Nano series microprocessor controllers position the actuator based on a reference input (set point). The PMR controller compares the preset set point with the current position of the actuator (actual value). In case the values differ from each other, the actuator is moved to the position specified by the set point. The actual value is determined by a potentiometer, integrated in the actuator.

Electrical connection

Protective measures shall be implemented in accordance with VDE (Association of German Electrotechnical Engineers) and EVU (Electricity Board) regulations. In particular, VDE Regulation 0105 "Working on Live Components" shall be followed.

For electrical installation, make sure to follow the enclosed wiring diagram.

Supply lines to microprocessor controller and actuator must meet the conductor cross-section as specified in the VDE regulations.

For low voltages (set point/actual value signalling cable) use **shielded** conductors of minimum cross-section 0.5 sq.mm. and maximum length of 1000 m.

Make sure to connect one end of the shielding to the housing mass (earthing terminal).

Never attempt to modify the internal wiring of the actuator.

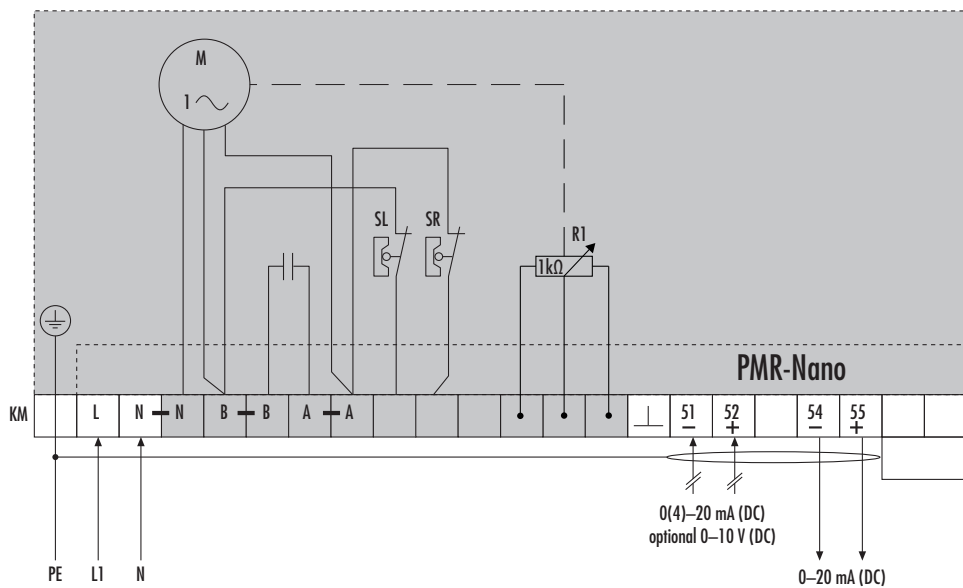


ADVICE

Never attempt to modify the internal wiring of the actuator.

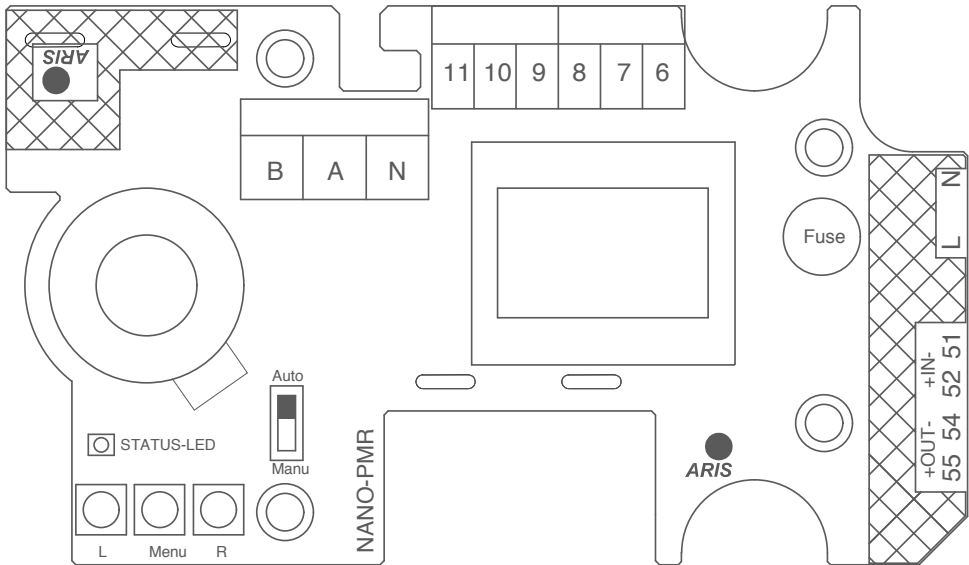
Wiring diagram (Built-in version)

KM	Terminal strip for microprocessor controller
M	Actuator motor
SL	Limit switch, CCW rotation
SR	Limit switch, CW rotation
R1	Potentiometer for actual value



	Internal wiring (do not modify!)
	External control and wiring

Circuit board



General information

This product is a controller for activation with standard signals. The PMR-Nano control board converts the standard signal in CW or CCW motor activation.

! ADVICE

Position limit switches and potentiometer are not preset upon delivery from factory.

According to the actuated fitting it is necessary to set position limit switches and potentiometer to the regulating distance (max. 90° at the output shaft of the actuator).

! ADVICE

Controller is delivered un-programmed from factory.

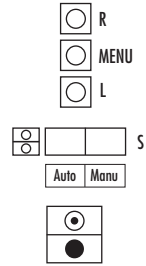
Through programming, set points must be assigned to the controller for the stop positions within the range of 0° and 90° (min. difference 18°). Once programming is completed, the positions within the range of the stop positions are approached as activated.

Operating controls and indicators

Status LED

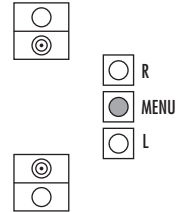


Controller not programmed
(Delivery condition or after reset)



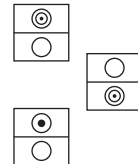
MANU (manual mode)

- Button LEFT: Actuator moving to the left (CCW)
- Button MENU: Activation > 5s ► Change in to programming mode
- Button RIGHT: Actuator moving to the right (CW)



AUTO (automatic mode)

- Buttons : No function
- LED indicator
 - Actuator moving to the left (CCW)
 - Actuator moving to the right (CW)
 - Position reached



Setting up stop positions and potentiometer

1. Set sliding switch **S** on PMR-Nano controller to **MANU** (manual).
2. Move the actuator with button **R** to the desired right (CW) stop position.
3. Set the respective control cam **R** for the position limit switch **SR** * in the sense of rotation of the control camshaft, so that switch **SR** is activated.
4. Move the actuator with button **L** to the desired left (CCW) stop position
5. Set the respective control cam **L** for the position limit switch **SL** * in the sense of rotation of the control camshaft, so that switch **SL** is activated.
6. Move the actuator with button **R** again to the desired right (CW) stop position.

With it, setting of stop positions and potentiometer is completed.

* see page 11 in manual for actuators of Nano series.

● Leuchtend	Bright	○ Dunkel	Dark	◉ Langsam blinkend	Slowly flashing	⦿ Schnell blinkend	Fast flashing
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Programming

- Before you start programming, setting of stop positions and potentiometer must be completed.
- Full programming must run through. Programming of single items, e.g. only actual values, is not possible.

Adjustment of set points/limit positions

- Allocation of limit positions to set points can be done via internally preset set points or externally applied set points.

1. Set sliding switch **S** on the PMR-Nano controller to **MANU** (manual).



2. Pressing the **MENU** key for 5 seconds you enter the programming mode and you will see the following short flashing signal on the LED indicator.



3. Move to the left limit stop position by activating the **L** button.



4. Confirm the position by activating the **MENU** button.



5. By activating buttons **L** or **R** you are able to allocate a corresponding set point to this limit stop position, which is visible by a color change of the LED.



● Leuchtend	Bright	○ Dunkel	Dark	◉ Langsam blinkend	Slowly flashing	◎ Schnell blinkend	Fast flashing
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Left set point

0mA

4mA

20mA

externally applied set point

Change with button L / R

R
 MENU
 L

6. Confirm selected set point with the **MENU** button

7. You will see the following short flashing signal on the LED indicator.

R
 MENU
 L

8. Move to the right limit stop position by activating the **R** button.

9. Confirm the position by activating the **MENU** button.

10. By activating buttons **L** or **R** you are able to allocate a corresponding set point to this limit stop position, which is visible by a color change of the LED.

R
 MENU
 L

R
 MENU
 L

R
 MENU
 L

Right set point

0mA

4mA

20mA

externally applied set point

Change with button L / R

R
 MENU
 L

Depending on the set point allocated to the left limit stop position, only logic settings are possible.

R
 MENU
 L

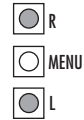
11. Confirm selected set point with the **MENU** button

R
 MENU
 L

Leuchtend	Bright	Dunkel	Dark	Langsam blinkend	Slowly flashing	Schnell blinkend	Fast flashing
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Setting up actual value output

12. By activating buttons **L** or **R** you select a corresponding actual value output, which is visible by a color change of the LED.



4..20mA



0..20mA



interchanging

Change with buttons **L / R**



13. Confirm selected actual value range by activating the **MENU** button.

Setting for actual value allocation to limit stop positions:

14. By activating buttons **L** or **R** you allocate 0(4)mA to the corresponding limit stop position.



Left end position 0/4mA



Right end position 0/4mA



Change with buttons **L / R**



15. Confirm selected actual value by activating the **MENU** button



With it, programming is completed.

You see the following flashing signal on the LED indicator.



● Leuchtend	Bright	○ Dunkel	Dark	● Langsam blinkend	Slowly flashing	● Schnell blinkend	Fast flashing
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To enter the automatic mode, move the sliding switch **S** to **AUTO**.



In case no external set point is present, the actuator moves to 0/4mA position!

By set point presetting 0(4) up to 20mA it is now possible to position the actuator as programmed.

RESET-OPTION

Deletes the stored data

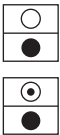
- With the controller in idle state keep the **MENU** button in **MANU** mode pressed



- Switch on controller, keep **MENU** button pressed for approx. 5s



- LED lights up in red ▶ Controller is initialized
- LED changes to
- Let button go



● Leuchtend	Bright	○ Dunkel	Dark	◉ Langsam blinkend	Slowly flashing	◎ Schnell blinkend	Fast flashing
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Technische Daten

Power supply:

230 V $\pm$ 10%, 50/60 Hz

Special voltages/frequencies see nameplate

Set point input:

— 0 (4) to 20 mA (DC)

Burden 250 Ω

Overload protection 630 mA

Reverse battery protection up to -630 mA.

ESD protection, input filter, resolution: 10 bit

Actual value output:

Optional limits between 0 and 20 mA (DC)

Current source, max. burden 500 Ω

Resolution: 10 bit

Subject to technical changes.



Declaration of Incorporation of partly completed machinery

according
EU directive 2006/42/EC Annex II B „Machinery Directive“

Herewith we declare, that the below mentioned incomplete machinery

Product description:	Electrical actuator
Product Types:	nano and identical

Fulfills the basic requirements of the annex I of the directive 2006/42/EC, if it applies to the appropriate order:

1.1.2c,e; 1.1.3; 1.1.5; 1.3.4; 1.5.1; 1.5.2; 1.5.4; 1.5.5; 1.5.6; 1.5.8; 1.5.9; 1.5.11; 1.6.1; 1.6.4; 1.7.3; 1.7.4

The following harmonized standards were applied:
DIN EN ISO 12100:2011-03 („Safety of machinery“)

The product is a partly completed machinery accordance with Article 2 letter g of the Directive 2006/42/EC. The special technical documents according to annex VII part B have been created. For reasonable requests these documents can be sent electronically to the responsible authorities.

Regarding the outgoing electrical hazards of the partly completed machinery, the safety objectives of directive 2006/95/EC („Low Voltage Directive“) are complied with in accordance with Annex I No. 1.5.1 of Directive 2006/42/EC. Applied harmonized standard:

DIN EN 61010-1:2011-07 („Safety requirements for electrical equipment for measurement, control, Control and laboratory use “)

The initial operation of this incomplete machinery is only permitted, if it is approved that the facility or machinery in which it will be installed corresponds to the EC directive 2006/42/EC, if it applies.

Authorized representative for collection of relevant technical documents:

Claudio Usai
Quality and product safety
ARIS Stellantriebe GmbH
Rotter Viehtrift 9
D-53842 Troisdorf

This declaration is invalid if the machinery is changed or rebuilt in a manner it was not designed for.

Troisdorf, 01. June 2014

C. Usai (Quality and product safety)

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